

COMP 382: Reasoning about Algorithms

# More NP-Complete Reductions and Approximation Algorithms

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# Today's Lecture

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## 1. Approximation Algorithms

- 1.1 2-Approximation Algorithm for Vertex Cover
- 1.2 (In)Approximability of TSP
- 1.3 Metric TSP and Its Approximation Algorithm

## 2. Set Cover

- 2.1 SET-COVER Is NP-Complete
- 2.2 Approximation Algorithm for Set Cover

Reading:

- Chapter 12 of the *Algorithms* book [Erickson, 2019]
- Chapter 8.1 of [Tardos and Kleinberg, 2005]

Content adapted from the same references.

# Approximation Algorithms

If we relax optimality, does it get easier?

# Approximation Algorithms

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- Run in polynomial time.
- Always produce a *feasible* solution.
- Guarantee that the solution is within a factor  $\alpha$  of the optimum.
- For minimization problems  $\alpha > 1$ , and smaller  $\alpha$  means better approximation.

$$\text{OPT} \leq \text{cost(ALG)} \leq \alpha \cdot \text{OPT}.$$

- For maximization problems  $\alpha < 1$ , and larger  $\alpha$  means better approximation.

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# Approximability of Problems

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Often we seek a solution that is *close* to optimal: a constant-factor approximation, or an  $\alpha$  that grows slowly with  $n$  (e.g.,  $\log n$ ).

A natural question:

Does every NP-hard optimization problem admit a polynomial-time approximation algorithm?

- Some problems *do* admit good approximations.
- Others remain hard even to approximate within any reasonable factor.

This leads to an entire area of study: **approximability theory**.

# **2-Approximation Algorithm for Vertex Cover**

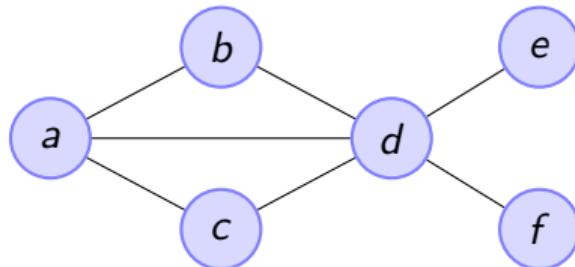
## Recap: Vertex Covers

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Let  $G = (V, E)$  be a simple undirected graph.

A **vertex cover** in  $G$  is a subset  $C \subseteq V$  such that every edge of  $G$  has at least one endpoint in  $C$ .

Equivalently: every edge is “touched” by  $C$ .



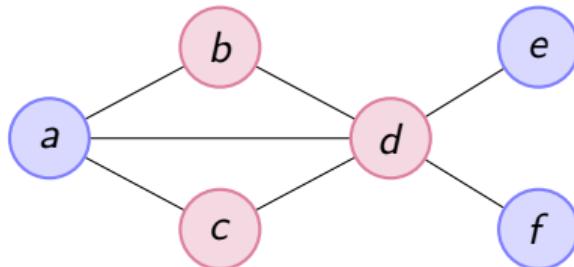
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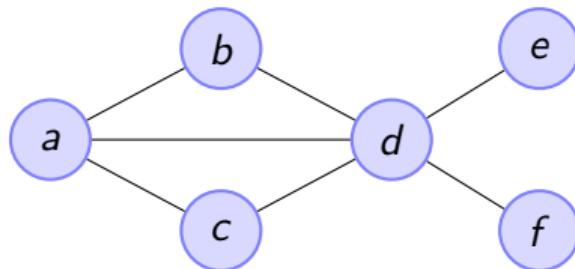
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A vertex cover  $C = \{b, c, d\}$  touches all edges.

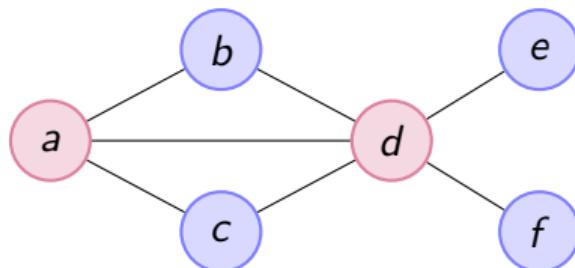
# Minimum Vertex Cover Problem

**VERTEX-COVER:** Given a graph  $G$  and an integer  $k$ , does  $G$  contain a vertex cover of size at most  $k$ ?



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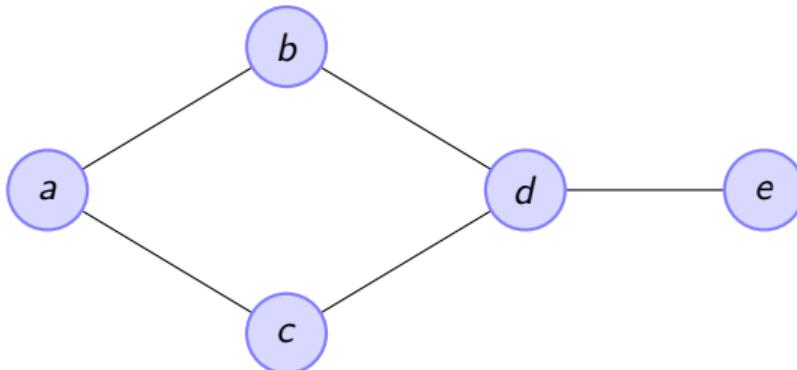


Here  $\{a, d\}$  is a vertex cover of size 2.

## 2-Approximation for Vertex Cover

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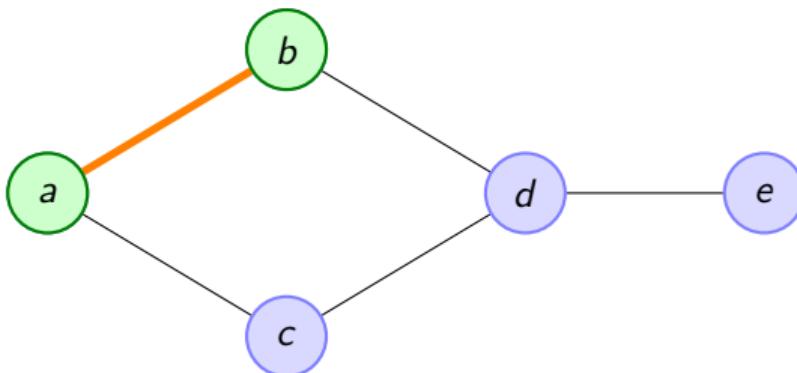
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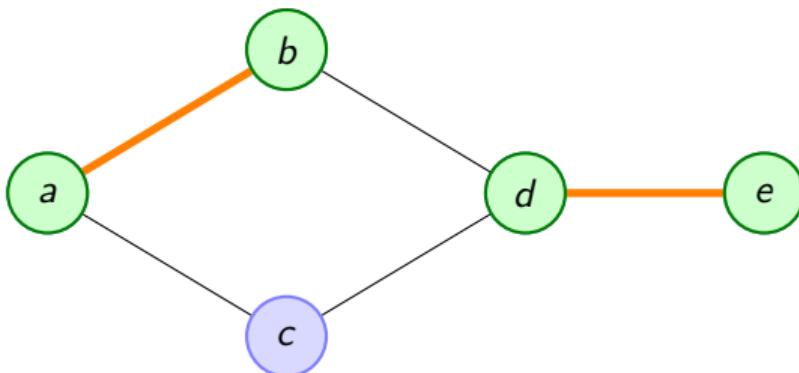


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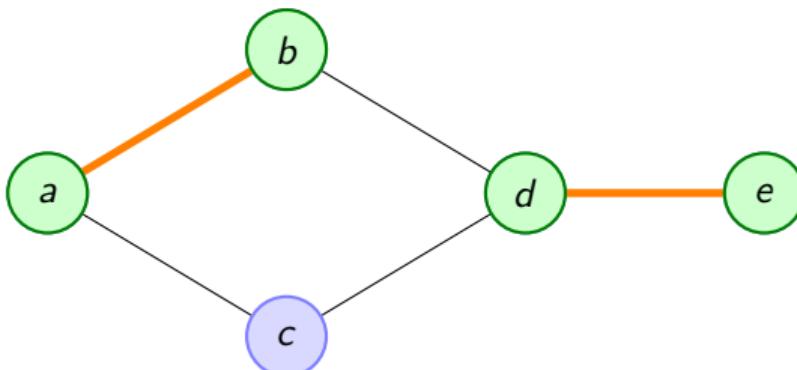
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Step 2: pick another uncovered edge (here  $(d, e)$ ), add  $d$  and  $e$ .

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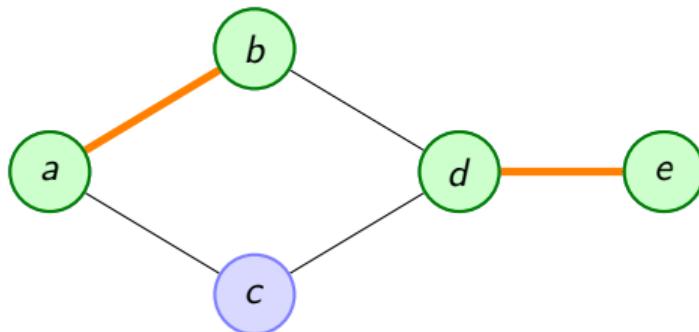
Step 2: pick another uncovered edge (here  $(d, e)$ ), add  $d$  and  $e$ .

All edges are covered.  $\Rightarrow$  Final cover =  $\{a, b, c, d\}$ .

# Why the Greedy Algorithm Is a 2-Approximation

---

- Let  $M$  be the set of edges the algorithm picks. They are pairwise disjoint  $\Rightarrow$  forming a matching.

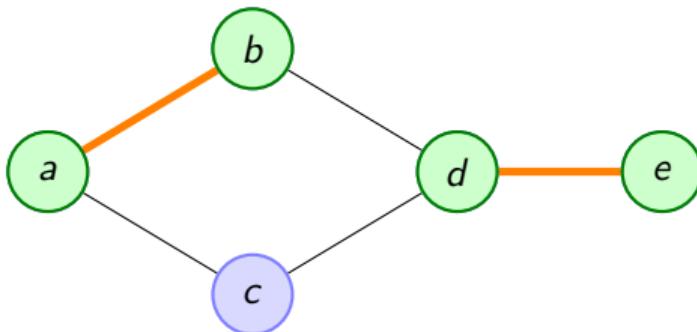


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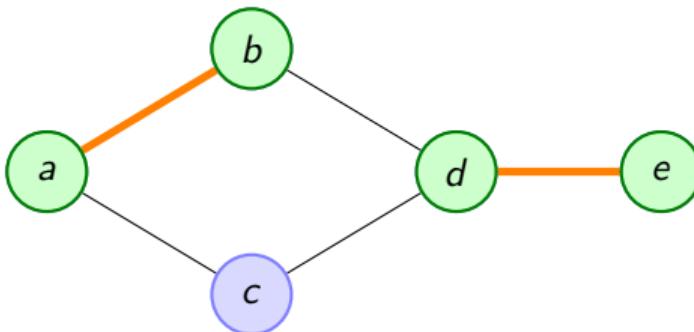


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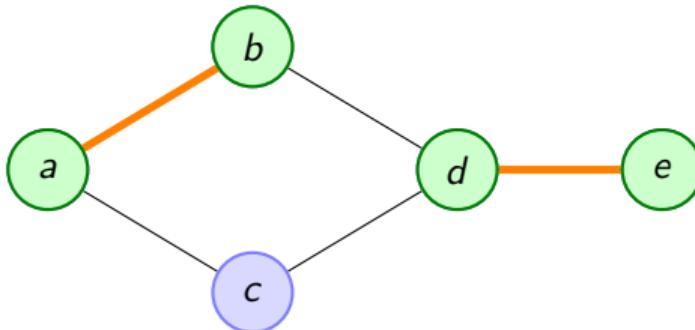
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- Therefore

$$|C_{\text{ALG}}| = 2|M| \leq 2|C^*|.$$



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# (In)Approximability of TSP

## Approximating TSP

---

**APPROX-TSP** Given a complete graph  $G$  and a constant  $\alpha > 1$ , output a tour in  $G$  with cost at most  $\alpha \cdot \text{OPT}$ .

Intuitively, this requirement is **weaker** than exact TSP.

- Any algorithm solving exact TSP automatically solves APPROX-TSP.

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However, APPROX-TSP and TSP have essentially the same difficulty.

# Inapproximability of TSP

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## Theorem

TSP admits *no* polynomial-time  $\alpha$ -approximation algorithm for any constant  $\alpha \geq 1$ , unless  $P = NP$ .

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**How do we prove this?** We return to our standard reduction recipe:

Reduce a known NP-complete problem (Hamiltonian Cycle) to APPROX-TSP.

## The Strategy: Distinguishing by Gap

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**Goal:** Reduce Hamiltonian Cycle to  $\alpha$ -Approx TSP.

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If an algorithm guarantees an  $\alpha$ -approximation, it returns a tour of cost  $C \leq \alpha \cdot \text{OPT}$ . We need a gap such that:

- **Case Yes (Hamiltonian):**  $\text{OPT} = n \implies C \leq \alpha n$ .
- **Case No (Not Hamiltonian):**  $\text{OPT} > \alpha n$ .

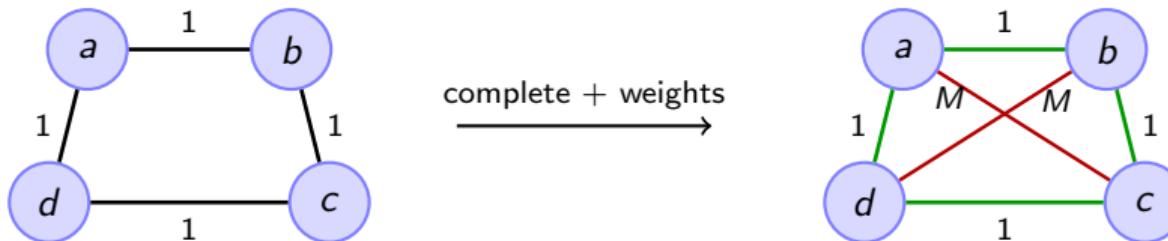
If we create this gap, checking if  $C \leq \alpha n$  decides the Hamiltonian Cycle problem.

# Creating the Gap

**Construction:** Build complete graph  $G'$  from  $G$  with weights:

$$w(u, v) = \begin{cases} 1 & \text{if } (u, v) \in E(G) \quad \text{(Original)} \\ M & \text{if } (u, v) \notin E(G) \quad \text{(Non-edge)} \end{cases}$$

where  $M$  is a large number (chosen later).



# Creating the Gap

---

## The Costs:

- **If  $G$  is Hamiltonian:** We use  $n$  edges of weight 1.  
 $\Rightarrow \text{OPT}(G') = n.$
- **If  $G$  is NOT Hamiltonian:** We must use at least one weight  $M$ .  
 $\Rightarrow \text{OPT}(G') \geq M + (n - 1).$

**Forcing the Gap:** Set  $M = \alpha n$ .

No Hamiltonian Cycle  $\implies \text{OPT}(G') \geq \alpha n + (n - 1) > \alpha n.$

# The Reduction Algorithm

## The Procedure

**Input:** Graph  $G$ , Approximation factor  $\alpha$ .

1. **Set the Penalty:** Let  $n = |V|$  and choose a large weight  $M = \alpha n + 1$ .
2. **Construct  $G'$ :** Create a complete graph where:
  - Existing edges in  $G$  get weight 1.
  - Missing edges (non-edges) get weight  $M$ .
3. **Run the Solver:** Let  $C$  be the cost returned by  $\text{APPROX-TSP}(G')$ .
4. **The Decision:**
  - If  $C \leq \alpha n \rightarrow$  Return **YES**.
  - If  $C > \alpha n \rightarrow$  Return **NO**.

# Proof of Correctness

---

We analyze the output based on the structure of  $G$ :

## Case 1: $G$ has a Hamiltonian Cycle

- The optimal tour uses only original edges:  $\text{OPT}(G') = n$ .
- The  $\alpha$ -approx algorithm returns cost  $C \leq \alpha \cdot \text{OPT}$ .
- Therefore,  $C \leq \alpha n$ .
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- Therefore,  $C \leq \alpha n$ .
- **Result:** Procedure correctly returns **YES**.

## Case 2: $G$ has NO Hamiltonian Cycle

- Any tour must use at least one non-edge (weight  $M$ ).
- Therefore,  $\text{OPT}(G') \geq M + (n - 1) > \alpha n$ .
- Since any tour cost  $C \geq \text{OPT}(G')$ , we have  $C > \alpha n$ .
- **Result:** Procedure correctly returns **NO**.

# **Metric TSP and Its Approximation Algorithm**

Turns out TSP is not so hopeless...

# Metric TSP

---

**Metric TSP** An input instance to Metric TSP is a complete graph where edge weights are a metric.

- **Identity of indiscernibles:**  $d(u, v) = 0 \Leftrightarrow u = v$ .
- **Non-negativity:**  $\forall u \neq v : d(u, v) > 0$ .
- **Symmetric:**  $d(u, v) = d(v, u)$ .
- **Triangle inequality:**  $\forall u, v, w : d(u, w) \leq d(u, v) + d(v, w)$ .

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## Why do we care?

- Many natural settings (FedEx, road networks, Euclidean distances) satisfy the triangle inequality.
- Triangle inequality enables good approximation algorithms.

## 2-Approximation for Metric TSP: MST Doubling

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Algorithm (“double-tree”):

1. Compute a Minimum Spanning Tree (MST)  $T$  of the metric.
2. Double every edge of  $T$  to get an Eulerian multigraph.
3. Take an Euler tour and *shortcut* repeated vertices to obtain a TSP tour.

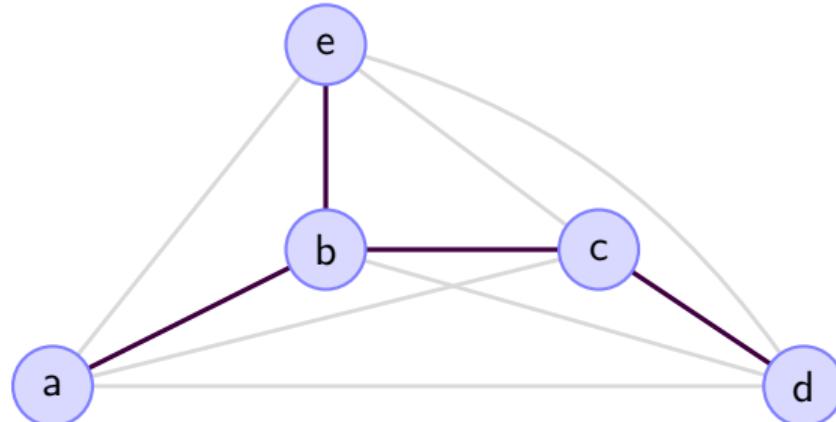
# Visualizing the Double-Tree Algorithm

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## Step 1: Metric MST

We compute the MST of the metric graph (shown in **purple**).

*Current Cost  $\leq$  OPT.*



Why?

$$W(MST) \leq W(\text{ Hamiltonian Path}) \leq W(\text{OPT Hamiltonian Cycle})$$

# Visualizing the Double-Tree Algorithm

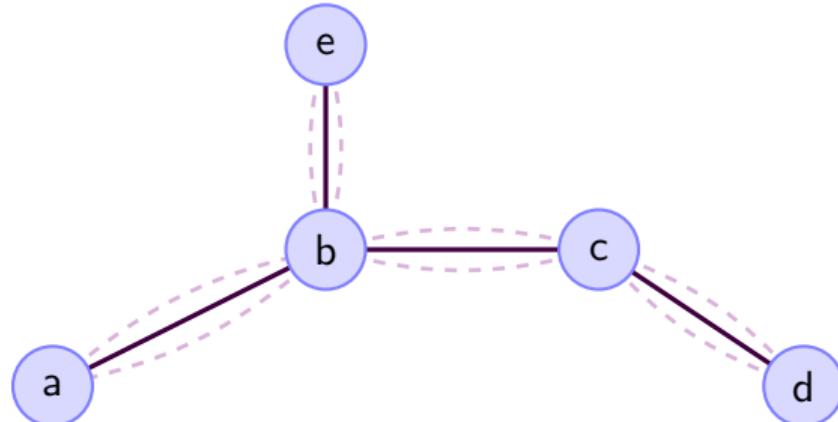
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## Step 2: Doubling

We double every edge in the MST.

This creates an **Eulerian Multigraph**  
(every node has even degree).

*Current Cost*  $\leq 2 \cdot \text{OPT}$ .



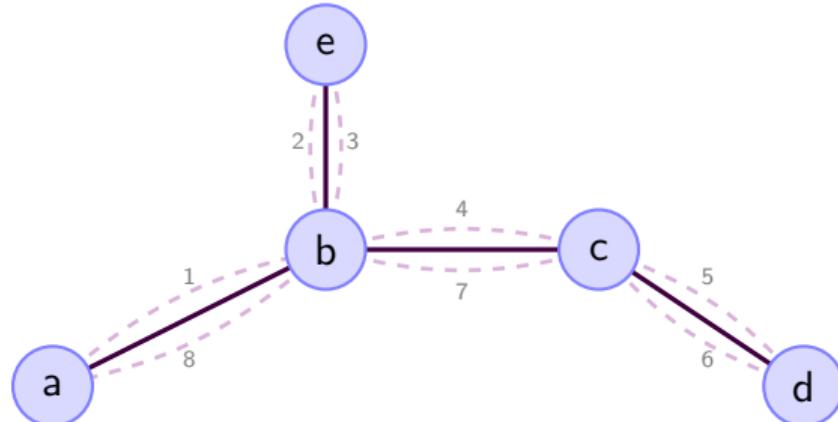
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## Step 3: Euler Tour

We traverse the doubled edges in a continuous loop (DFS order).

$a \rightarrow b \rightarrow e \rightarrow b \rightarrow c \rightarrow d \rightarrow c \rightarrow b \rightarrow a$

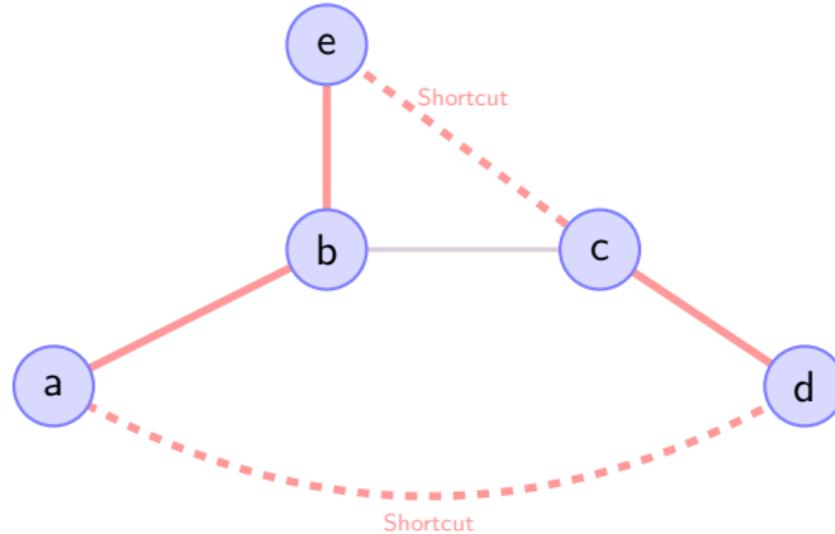


# Visualizing the Double-Tree Algorithm

## Step 4: Shortcutting

We delete repeated vertices from the Euler Tour. Thanks to the triangle inequality, taking a shortcut (red) is always cheaper.

**Final Tour:**  $a \rightarrow b \rightarrow e \rightarrow c \rightarrow d \rightarrow a$



$$W(\text{Tour with shortcuts}) \leq 2 W(\text{MST}) \leq 2 W(\text{OPT Hamiltonian Cycle}).$$

2-Approximation!

# Set Cover

# NP-Hard and NP-Complete Problems

---

## NP-Hard Problem

A problem  $B$  is **NP-hard** if for every problem  $A \in \text{NP}$ ,  $A$  reduces to  $B$ .

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## NP-Complete Problem

A problem  $B$  is **NP-complete** if:

1.  $B \in \text{NP}$ , and
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# The NP-Completeness Recipe

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To show a new problem  $B$  is NP-complete, start from a known NP-complete problem  $A$ .  
Show a polynomial-time reduction from  $A$  to  $B$ .

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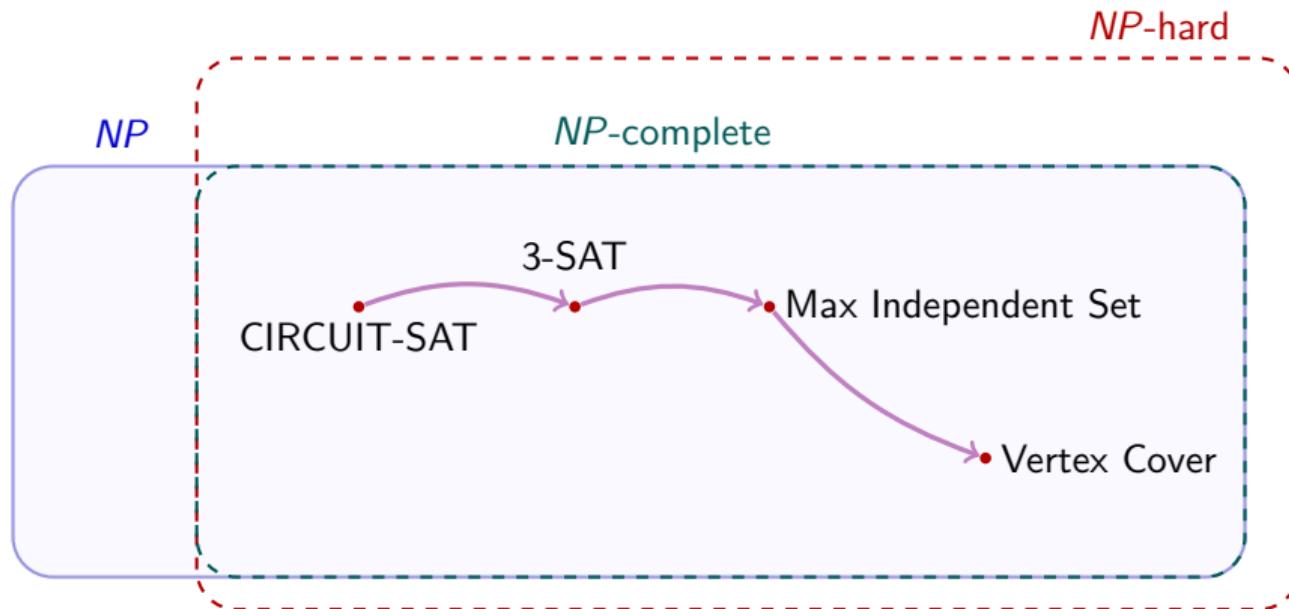
$B$  is NP-hard.

If we also show that  $B$  is in NP, then  $\implies$

$B$  is NP-complete

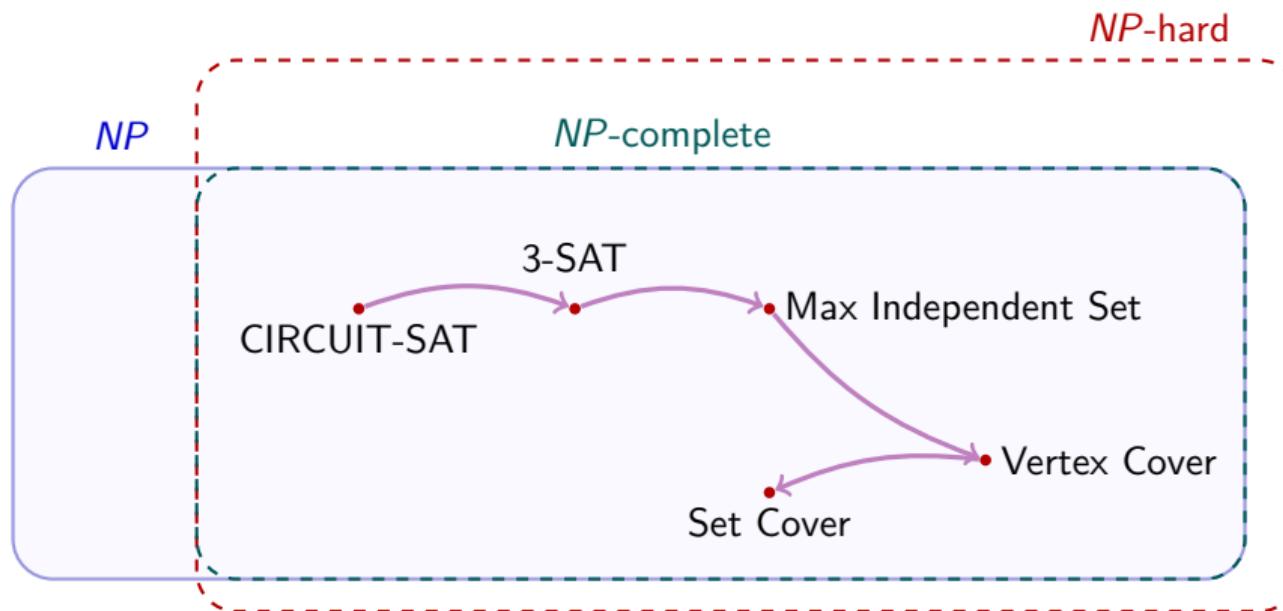
# A Small NP-Completeness Family Portrait

Once one natural problem is shown NP-complete, the others follow by reductions.



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# **SET-COVER Is NP-Complete**

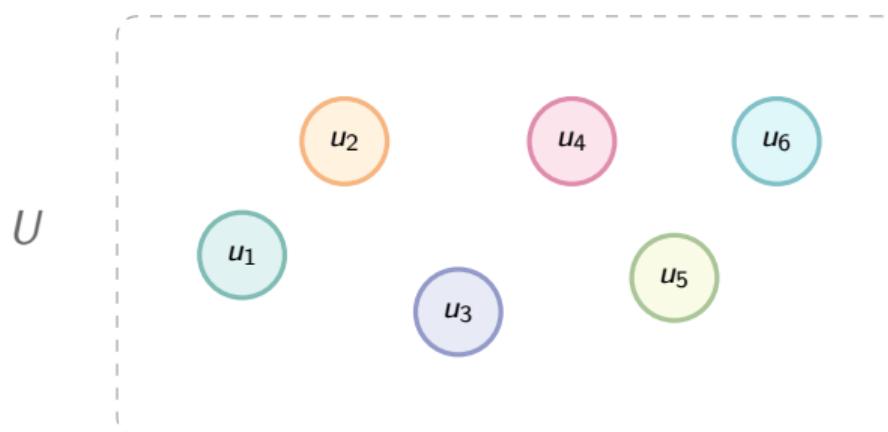
A reduction from VERTEX-COVER

# Set Cover

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Let  $U$  be a finite set of  $n$  elements.

And, let  $\mathcal{S} = \{S_1, \dots, S_m\}$  be a family of subsets with  $S_i \subseteq U$ .



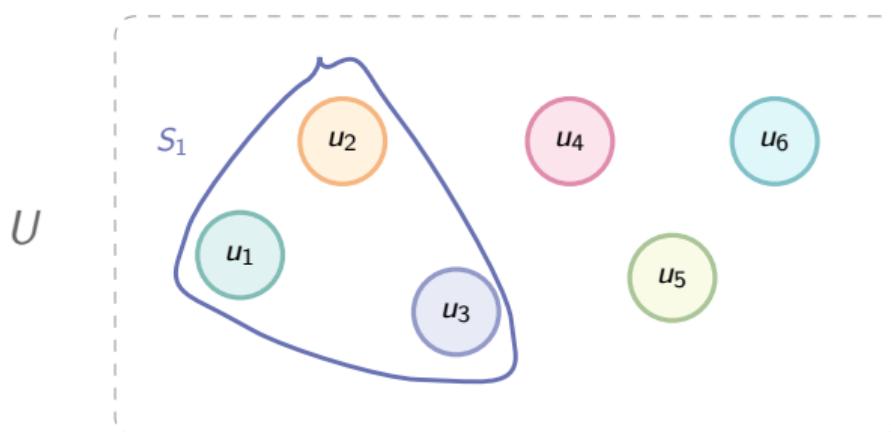
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Example:  $S_1 = \{u_1, u_2, u_3\}$        $S_2 = \{u_2, u_4, u_5\}$        $S_3 = \{u_3, u_4, u_5, u_6\}$



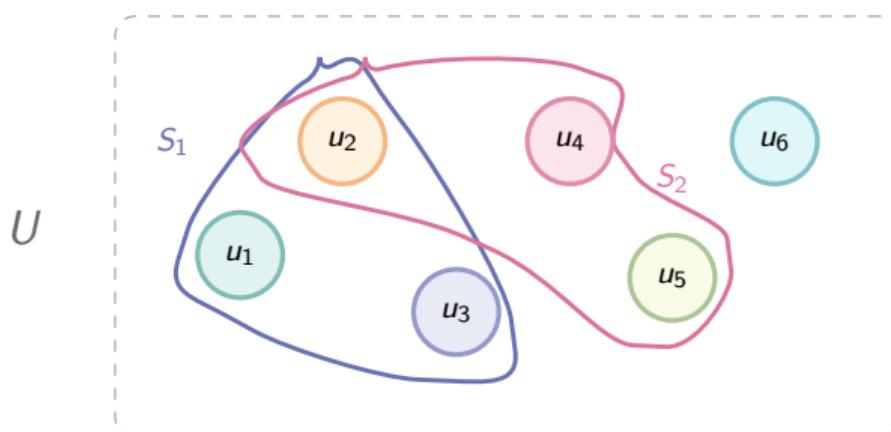
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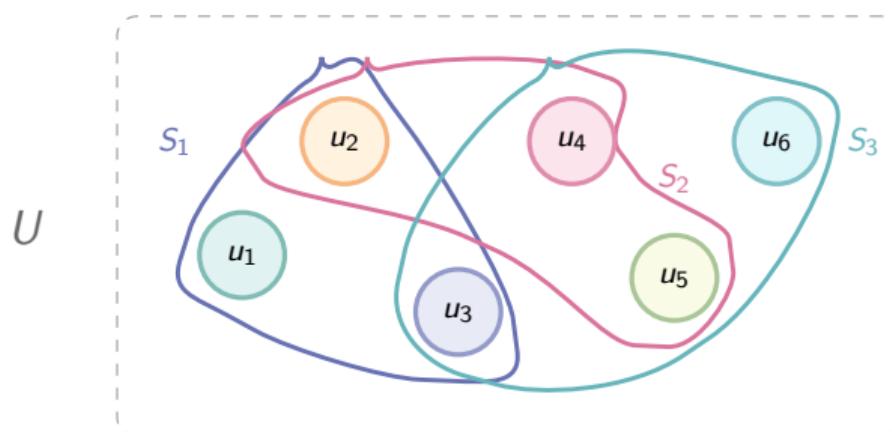
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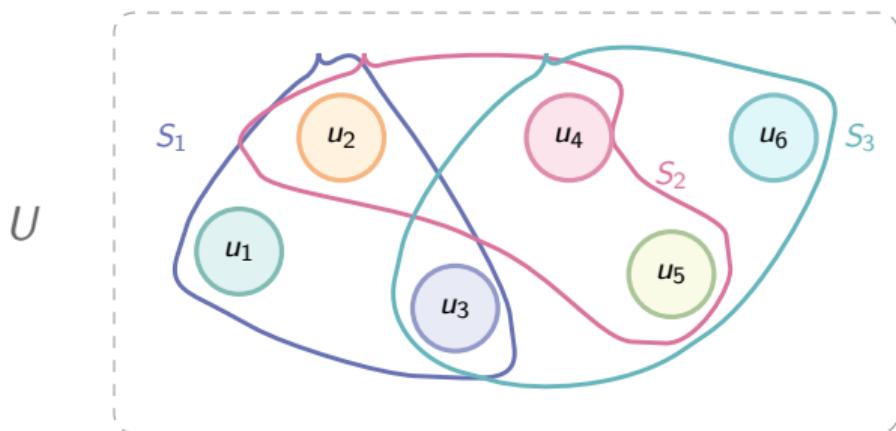


## Set Covers

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A **set cover** is a subfamily  $C' \subseteq \mathcal{S}$  such that every element of  $U$  lies in at least one member of  $C'$ .

Equivalently: the union of the chosen sets equals  $U$ .

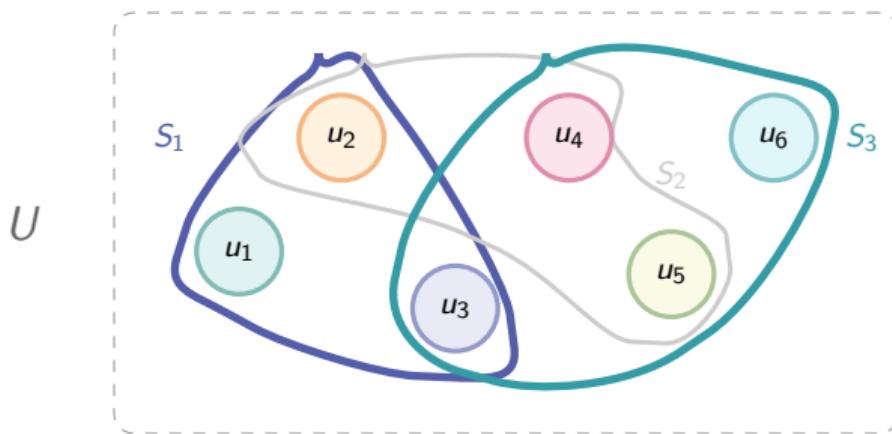


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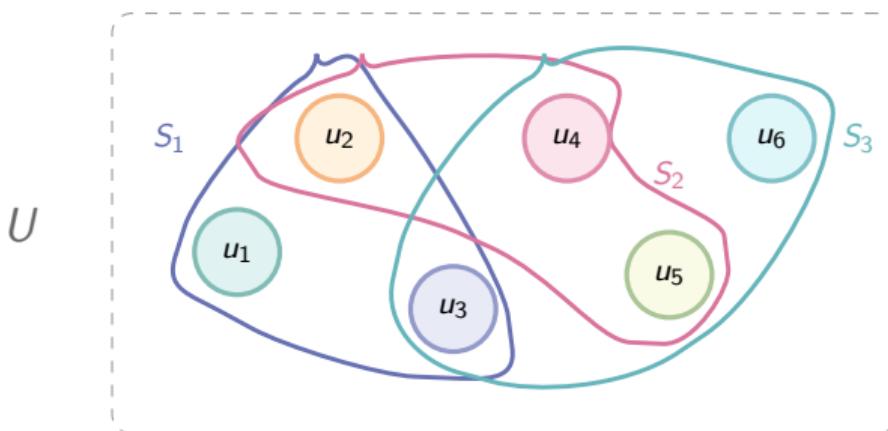
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A set cover is, for example,  $C' = \{S_1, S_3\}$  since  $S_1 \cup S_3 = U$ .

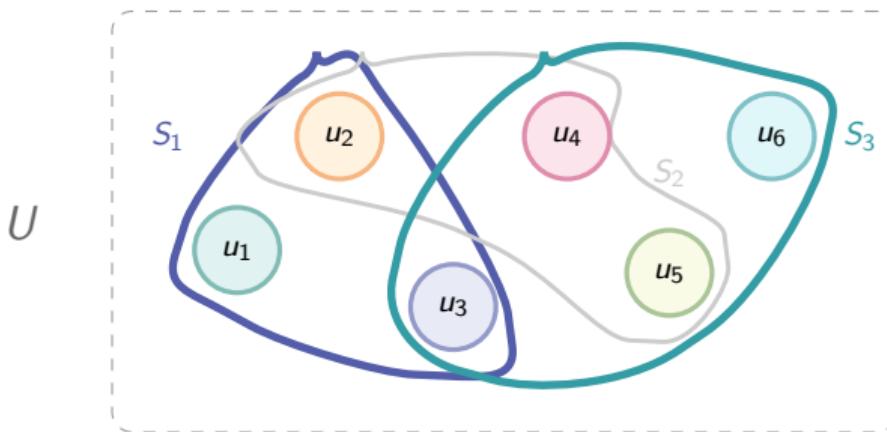
# Set Cover (Decision Problem)

**SET-COVER:** Given a universe  $U$ , a family  $\mathcal{S} = \{S_1, \dots, S_m\}$  with  $S_i \subseteq U$ , and an integer  $k$ , does there exist a subfamily of size at most  $k$  whose union equals  $U$ ?



# Set Cover (Decision Problem)

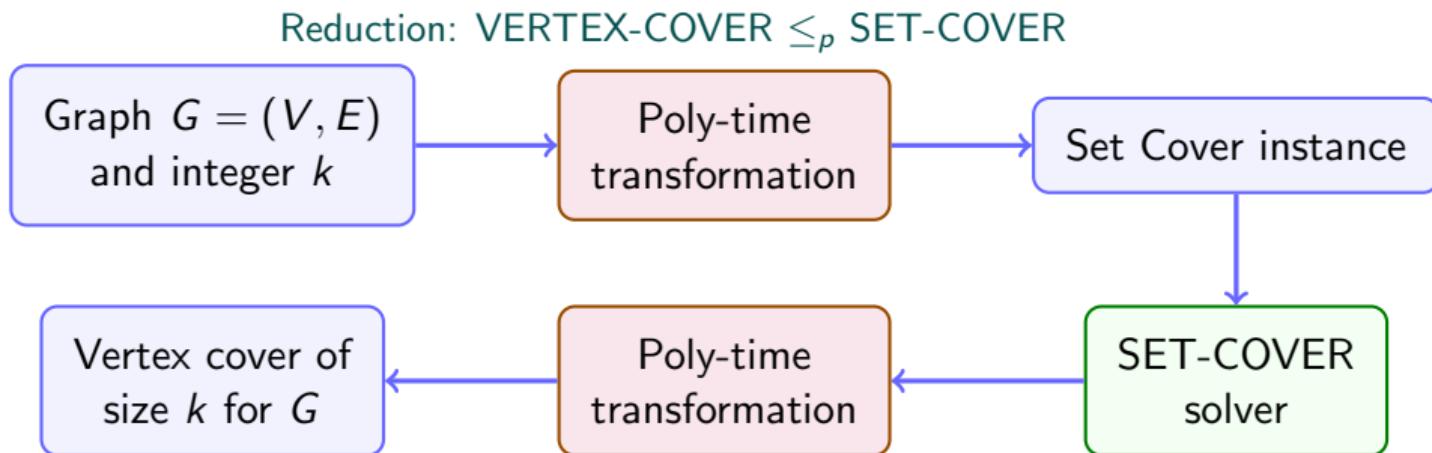
**SET-COVER:** Given a universe  $U$ , a family  $\mathcal{S} = \{S_1, \dots, S_m\}$  with  $S_i \subseteq U$ , and an integer  $k$ , does there exist a subfamily of size at most  $k$  whose union equals  $U$ ?



Here  $k = 2$  and  $\{S_1, S_3\}$  is a valid cover.

# Plan: Reduce VERTEX-COVER to SET-COVER

- Input on the Vertex Cover side: An undirected graph  $G = (V, E)$  and an integer  $k$ .
- We will build a Set Cover instance such that  $G$  has a vertex cover of size  $k$  iff  $(U, \mathcal{S}, k)$  has a set cover of size  $k$ .

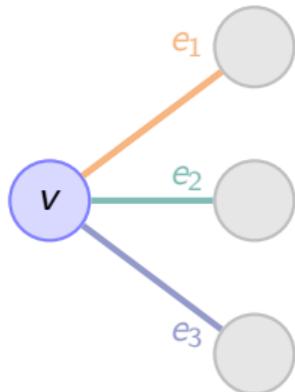


# The Resemblance: Vertex Cover vs. Set Cover

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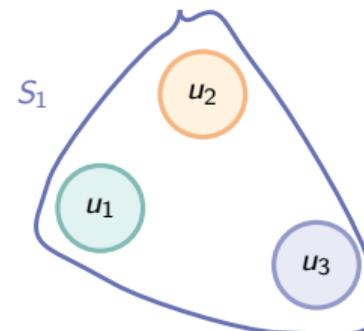
## Vertex Cover

- **Items to cover:** Edges.
- **Objects to use:** Vertices.



## Set Cover

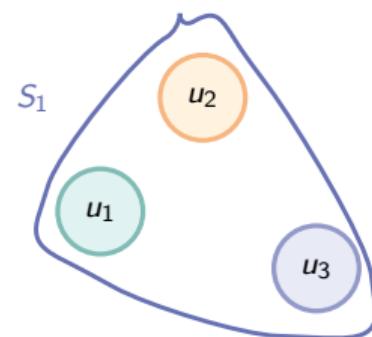
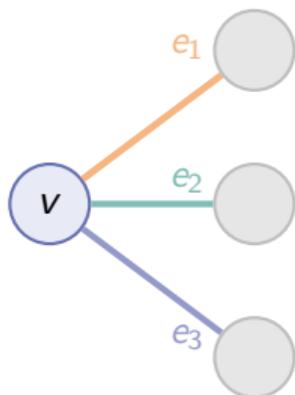
- **Items to cover:** Elements.
- **Objects to use:** Sets.



## The Resemblance: Vertex Cover vs. Set Cover

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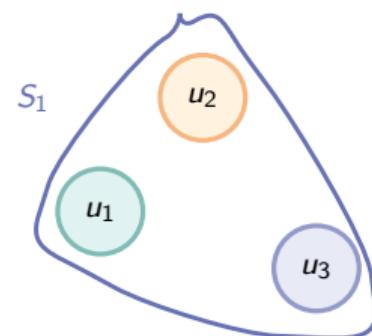
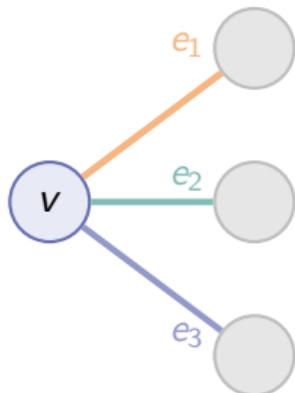
- Vertex Cover is essentially a **special case** of Set Cover.



## The Resemblance: Vertex Cover vs. Set Cover

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- Vertex Cover is essentially a **special case** of Set Cover.
- Vertex Cover: cover all edges using the graph's vertex sets (each edge has 2 options).
- Set Cover: cover all elements using arbitrary sets (no limit on set size).



## The Reduction: Vertex-Cover $\leq_p$ Set-Cover

---

Given a graph  $G = (V, E)$  and integer  $k$ , we build a Set Cover instance:

- The **universe** is the set of edges:

$$U := E.$$

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$$S_v := \{ e \in E : e \text{ is incident to } v \}.$$

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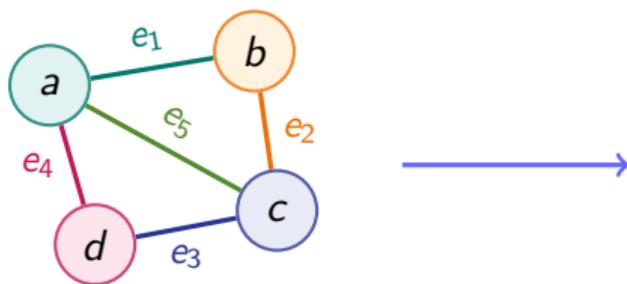
$$\mathcal{S} = \{S_v : v \in V\}.$$

- The Set Cover instance asks:

$$\exists C' \subseteq \mathcal{S} \text{ of size } \leq k \text{ such that } \bigcup_{S \in C'} S = U?$$

# The Reduction: VERTEX-COVER $\leq_p$ SET-COVER

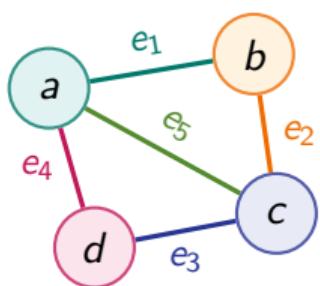
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Graph  $G$

# The Reduction: VERTEX-COVER $\leq_p$ SET-COVER

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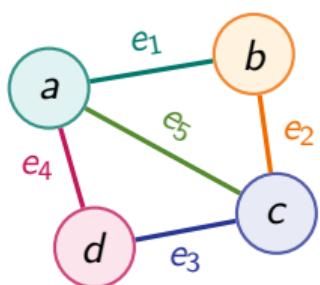
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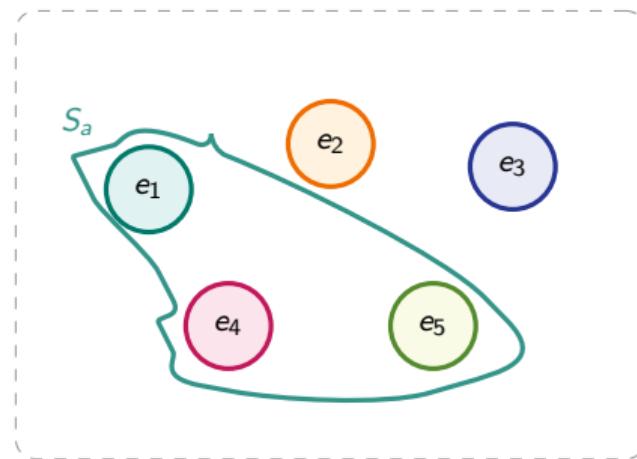
$$U = E$$

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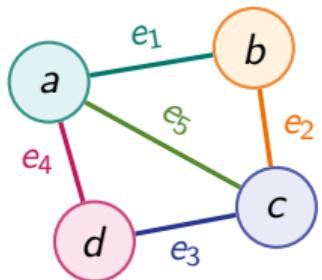
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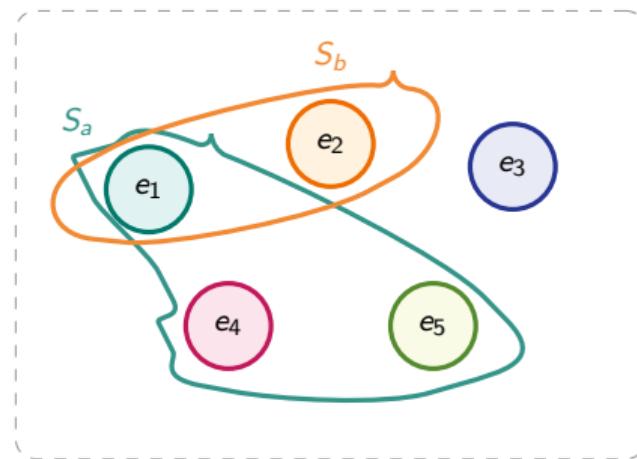
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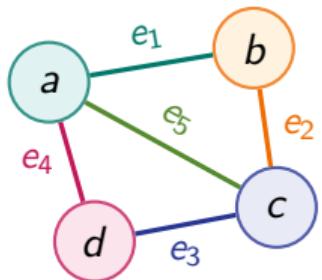
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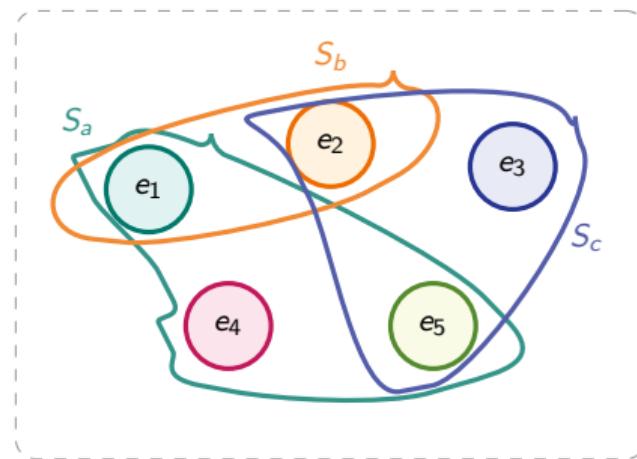
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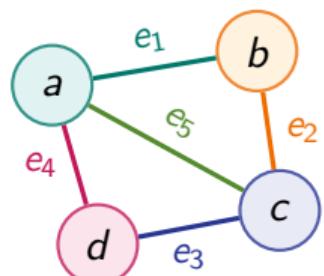


Graph  $G$

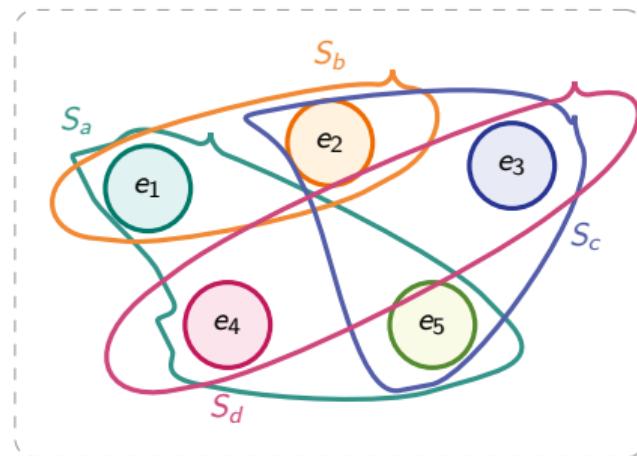


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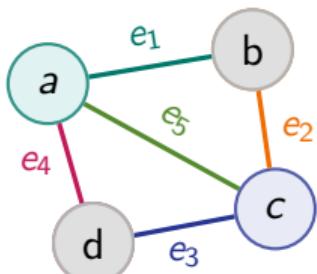


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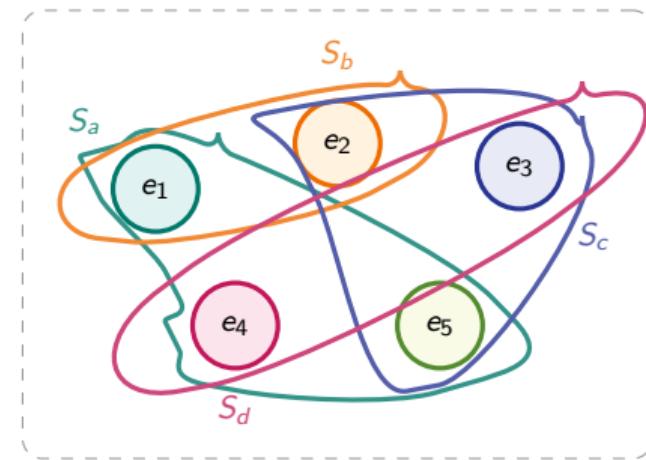


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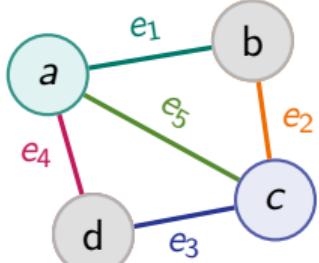
Graph  $G$



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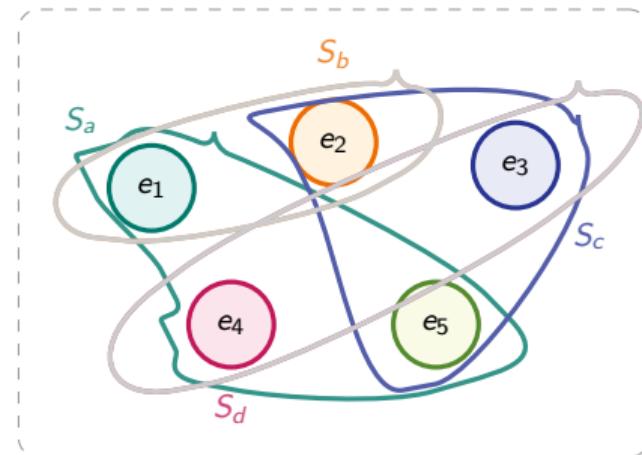
smallest vertex cover:  $C = \{a, c\}$

# The Reduction: VERTEX-COVER $\leq_p$ SET-COVER



Graph  $G$

smallest vertex cover:  $C = \{a, c\}$



$$U = E$$

smallest set cover:  $C' = \{S_a, S_c\}$

## Correctness of the Reduction

---

To prove the reduction is correct, we must show that the two instances have the same answer.

( $\Rightarrow$ ) Suppose  $C \subseteq V$  is a vertex cover of size at most  $k$ . Every edge  $e = \{u, v\} \in E$  has at least one endpoint in  $C$ .

Thus every element  $e \in U$  is contained in at least one of the sets  $C' = \{S_v : v \in C\}$ , meaning these  $|C| \leq k$  sets form a valid set cover.

( $\Leftarrow$ ) Suppose we have a set cover  $C' = \{S_{v_1}, \dots, S_{v_t}\}$  with  $t \leq k$ . Since  $C'$  covers all elements of  $U = E$ , for every edge  $e = \{u, v\}$ , at least one of the sets  $S_{v_i}$  contains  $e$ . However,  $e \in S_{v_i}$  exactly when  $v_i$  is an endpoint of  $e$ .

Therefore the vertices  $C = \{v_1, \dots, v_t\}$  touch every edge of  $G$ , so  $C$  is a vertex cover of size at most  $k$ .

## Correctness of the Reduction

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**Efficiency.** The construction is polynomial-time:

$$|U| = |E|, \quad |S| = |V|, \quad \text{each edge is added to exactly two sets.}$$

**SET-COVER is in NP.** A certificate is a subfamily  $\{S_{i_1}, \dots, S_{i_t}\}$  with  $t \leq k$ . A polynomial-time verifier checks:

- $t \leq k$ ,
- for every  $u \in U$  there exists  $j$  with  $u \in S_{i_j}$ .

**Conclusion.** Since VERTEX-COVER is NP-complete and we have given a polynomial-time reduction from VERTEX-COVER to SET-COVER, it follows that SET-COVER is NP-hard. Since it is also in NP, SET-COVER is NP-complete.

# Approximation Algorithm for Set Cover

# Greedy Algorithm for Set Cover

---

**Greedy rule:** At each step, pick the set that covers the *largest number of currently uncovered* elements. Break ties arbitrarily; repeat until all elements are covered.

## The Algorithm:

1. Initialize  $C \leftarrow \emptyset$  and  $U_{\text{left}} \leftarrow U$ .

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3. Return  $C$ .

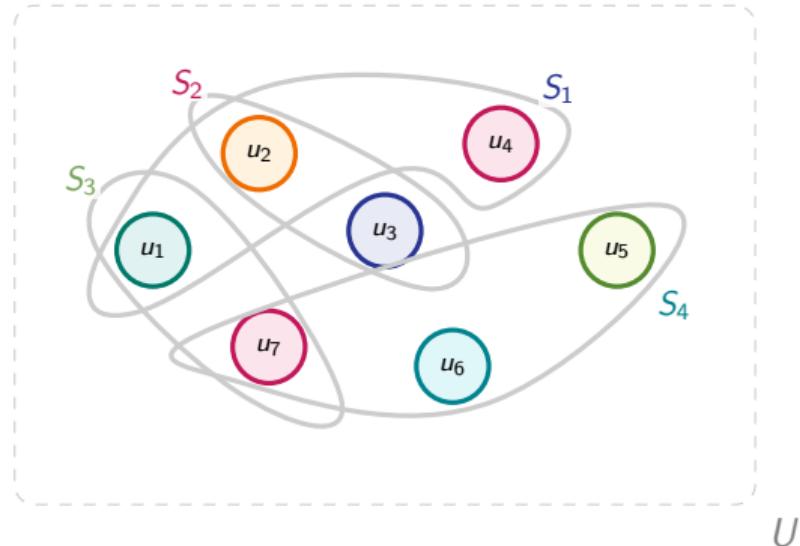
# Greedy Set Cover Approximation

## Algorithm Status:

Pick set with max *uncovered* elements.

Set	Elements	Count
$S_1$	$u_1$ , $u_2$ , $u_4$	3
$S_4$	$u_5$ , $u_6$ , $u_7$	3
$S_2$	$u_2$ , $u_3$	2
$S_3$	$u_1$ , $u_7$	2

Initial State: All elements uncovered.



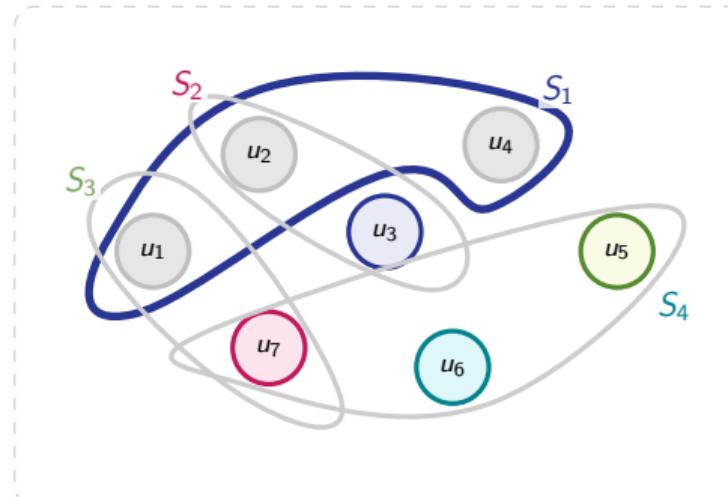
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$S_4$	$u_5, u_6, u_7$	3
$S_2$	$u_2, u_3$	1
$S_3$	$u_1, u_7$	1
$S_4$	Selected	–

**Step 1:** Pick  $S_1$ . Covers  $\{u_1, u_2, u_4\}$ .



$U$

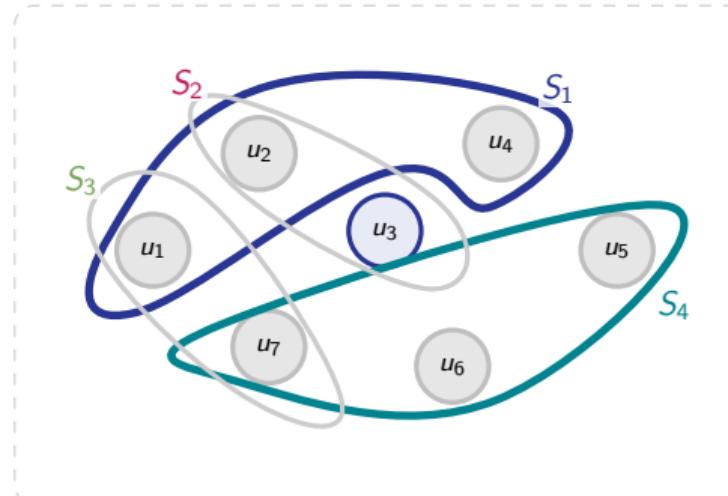
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## Algorithm Status:

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Set	Elements	Count
$S_2$	$u_2, u_3$	1
$S_3$	$u_1, u_7$	0
$S_1$	Selected	–
$S_4$	Selected	–

**Step 2:** Pick  $S_4$ . Covers  $\{u_5, u_6, u_7\}$ .



$U$

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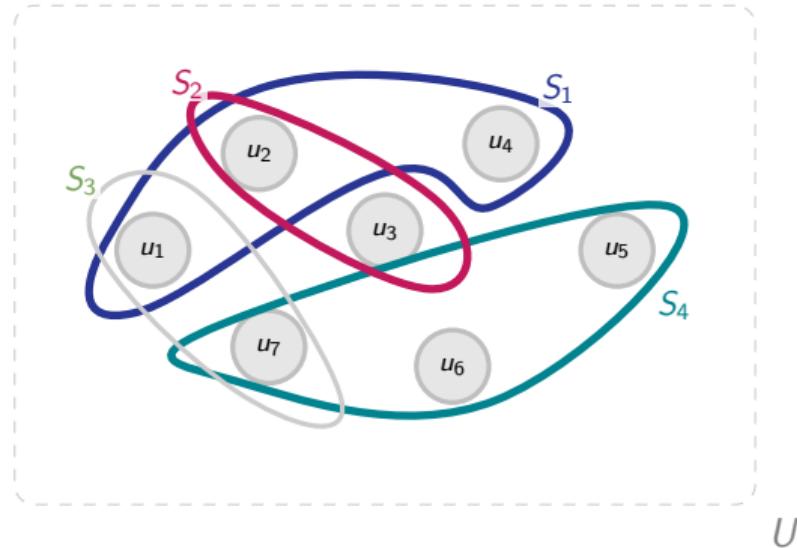
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$S_3$	$u_1, u_7$	0
$S_1$	Selected	—
$S_4$	Selected	—
$S_2$	Selected	—

**Step 3:** Pick  $S_2$ . Covers  $\{u_3\}$ .

**Done!** All elements covered.



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- Greedy picks a set covering *at least this many*.

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- After  $k$  steps:

$$t_k \leq t_{k-1} \left(1 - \frac{1}{\text{OPT}}\right) \leq t_{k-2} \left(1 - \frac{1}{\text{OPT}}\right)^2 \leq \dots \leq n \left(1 - \frac{1}{\text{OPT}}\right)^k < n e^{-k/\text{OPT}}.$$

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- If  $k$  is sufficiently large then the number of uncovered elements should drop below 1:

$$k = \lceil \text{OPT} \cdot \ln n \rceil \implies t_k < n e^{-\text{OPT}} \leq 1.$$

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Thus greedy uses at most  $(\ln n + 1) \cdot \text{OPT}$  sets.

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- This is optimal up to constants unless  $P = NP$ .

# References

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-  Tardos, E. and Kleinberg, J. (2005).  
*Algorithm Design*.  
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